

Monitoring Spectral Lines to calibrate LIGO data



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Outline (0/5)

- Introduction to Gravitational Waves and LIGO
- Introduction to LIGO Differential Arm Length (DARM) Actuation
- DARM Control Loop
- Photon Calibrator
- Spectral Line Monitor upgrades

Outline (1/5)

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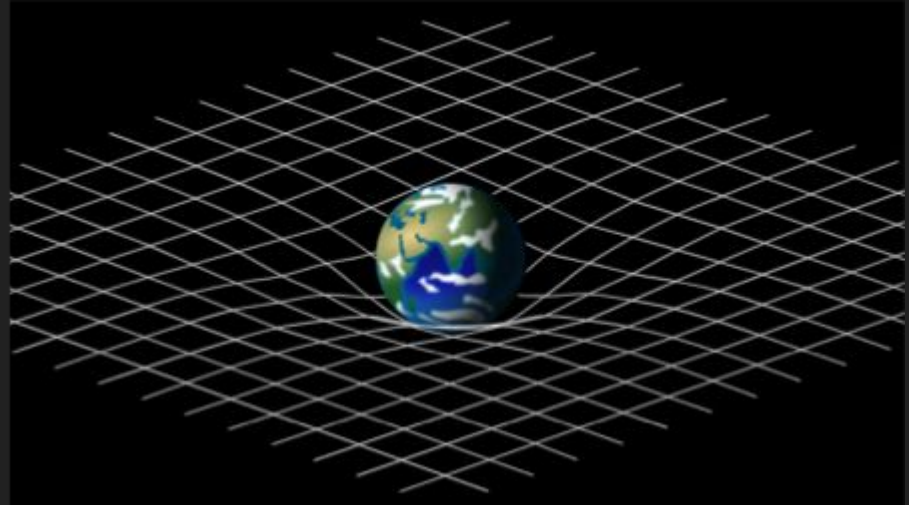
Newtonian Gravity



Newtonian Gravity

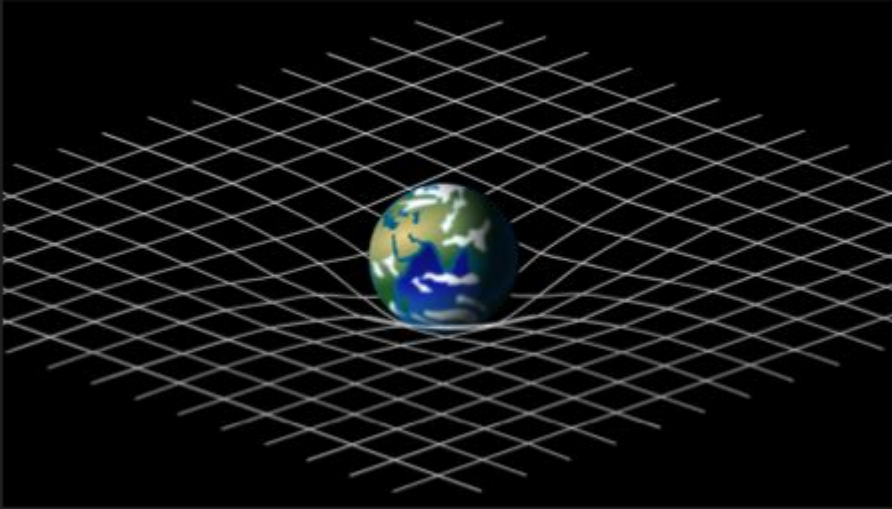


Einsteinian Gravity



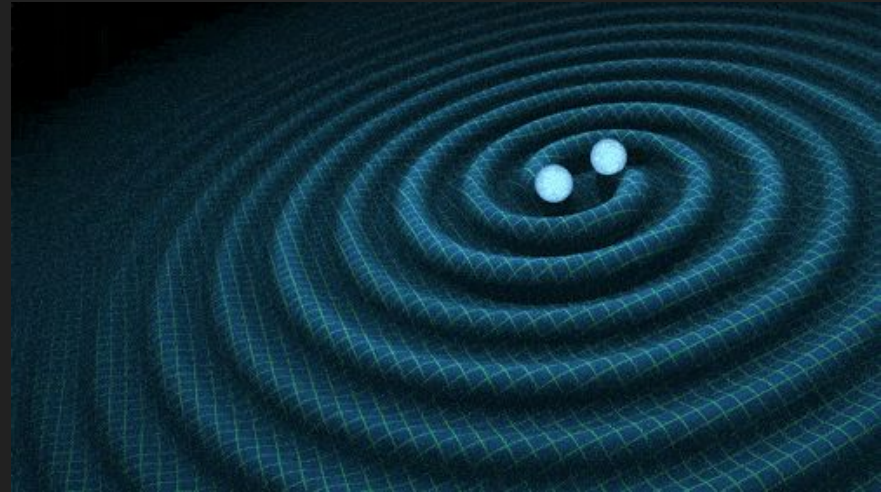
Gravity is the curvature/warping of space and time (collectively spacetime) due to the presence of matter and energy

Static Spacetime



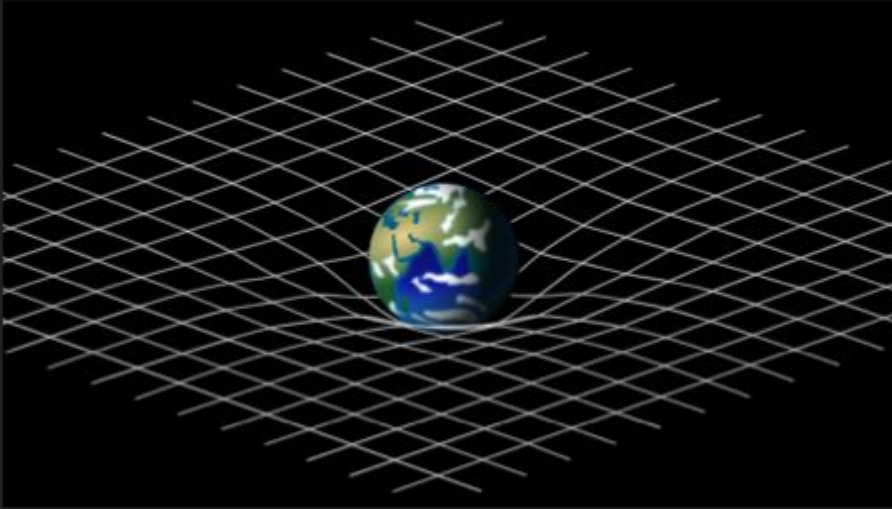
<https://commons.wikimedia.org>

Dynamic Spacetime



Credit: R. Hurt/Caltech/JPL

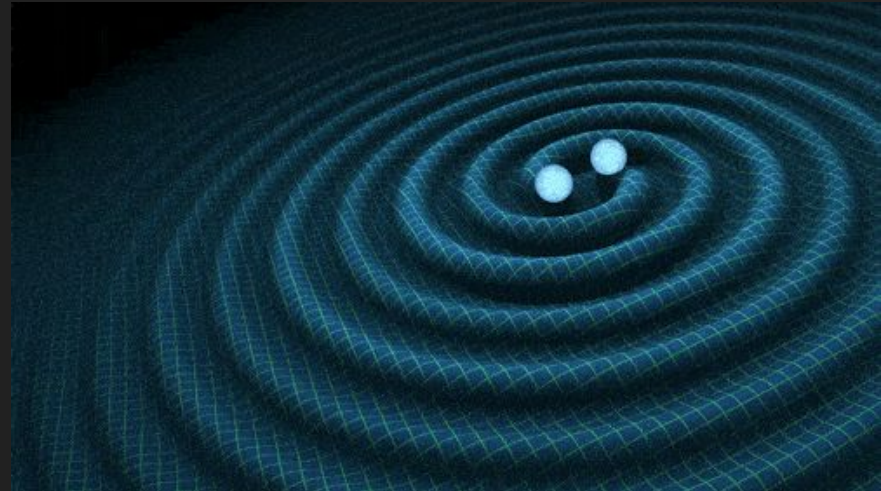
Static Spacetime



<https://commons.wikimedia.org>

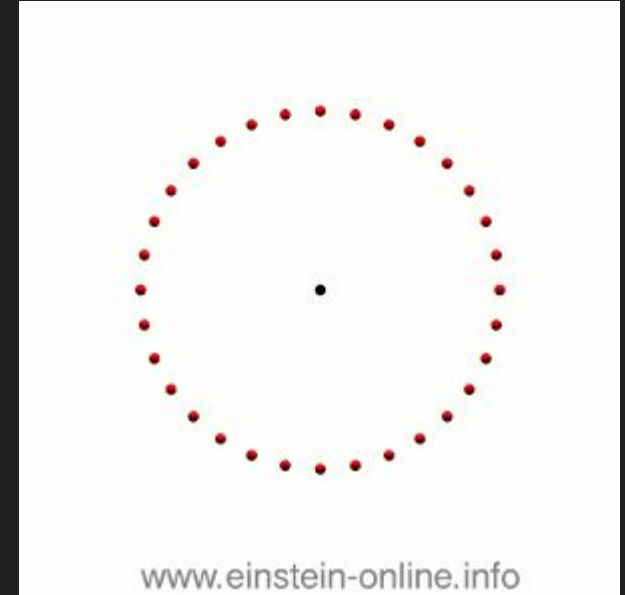
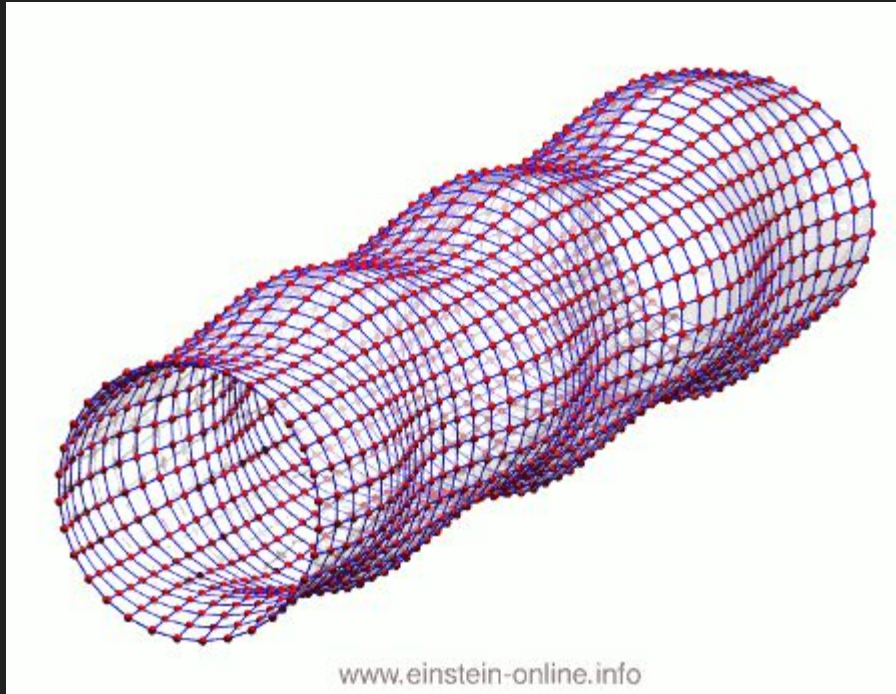
This is what LIGO detects

Dynamic Spacetime



Credit: R. Hurt/Caltech/JPL

Signature of a Gravitational Wave on Earth



The LIGO Detectors

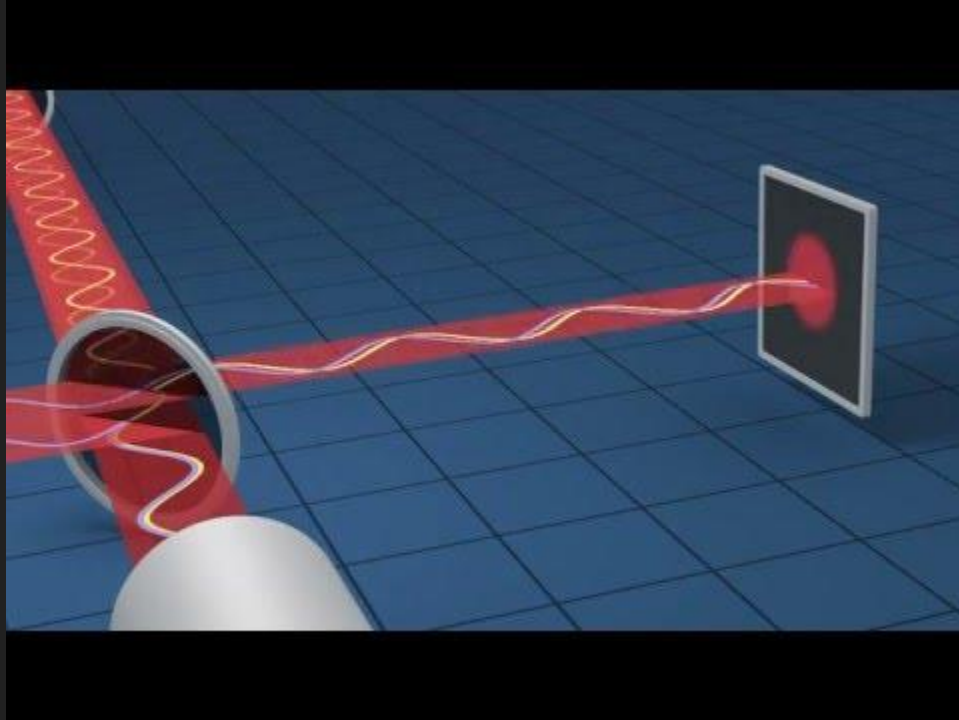


Hanford, WA



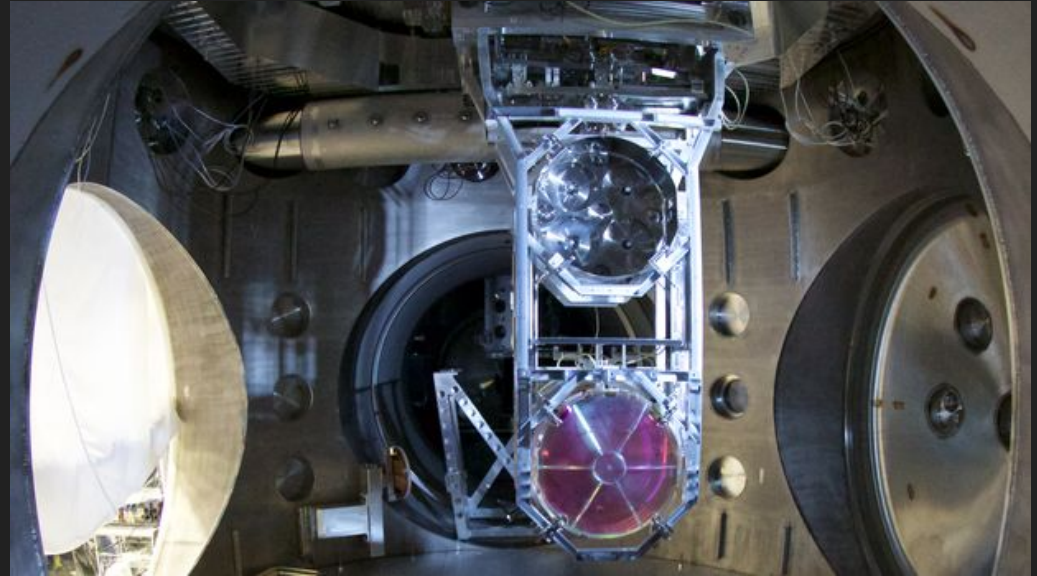
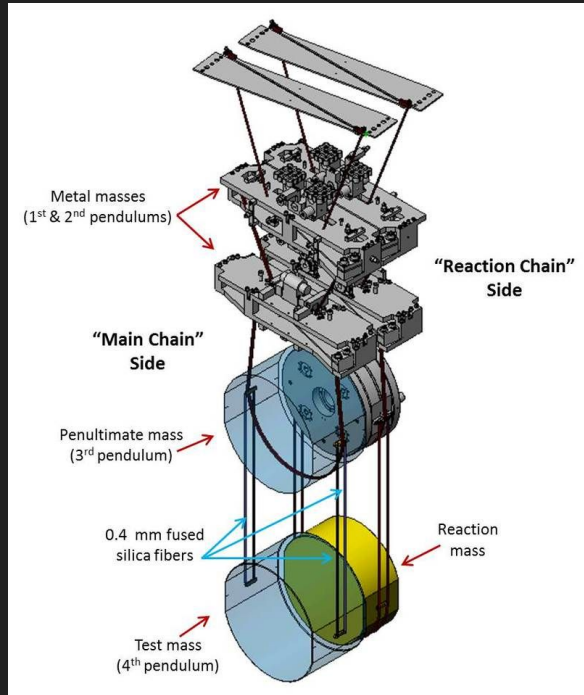
Livingston, LA

LIGO uses differential arm motion to measure the displacement of spacetime



Displacements
on the order of
 10^{-18} meters!

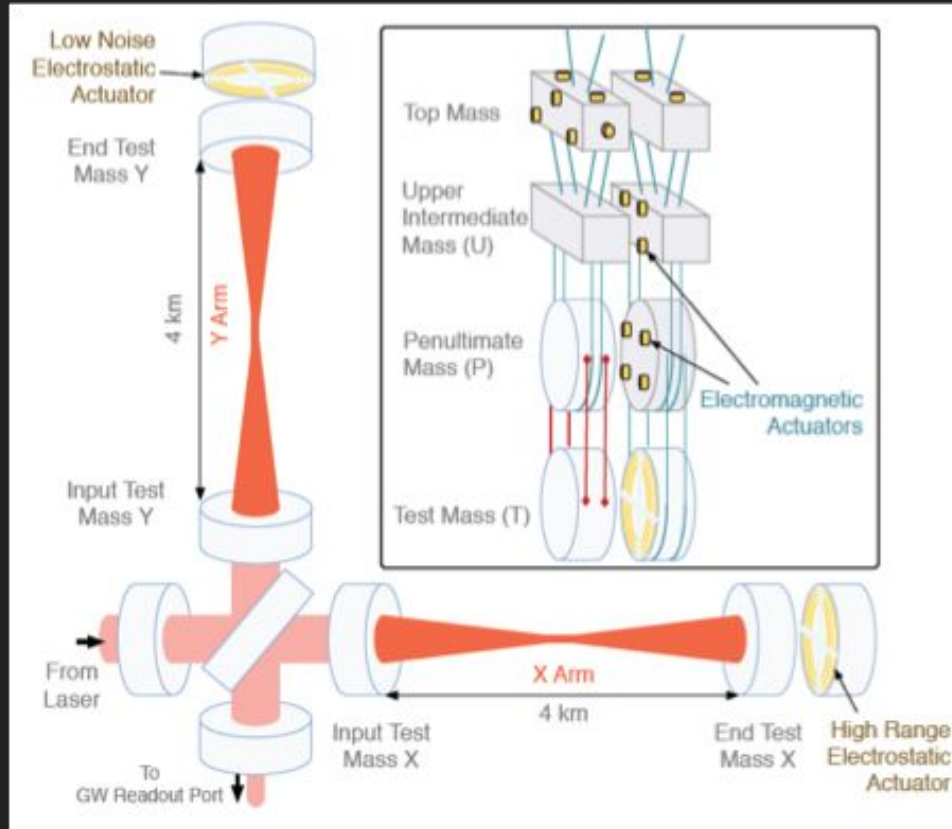
The LIGO Test Masses (mirrors) are hung on a quad-suspension pendulum to reduce seismic noise



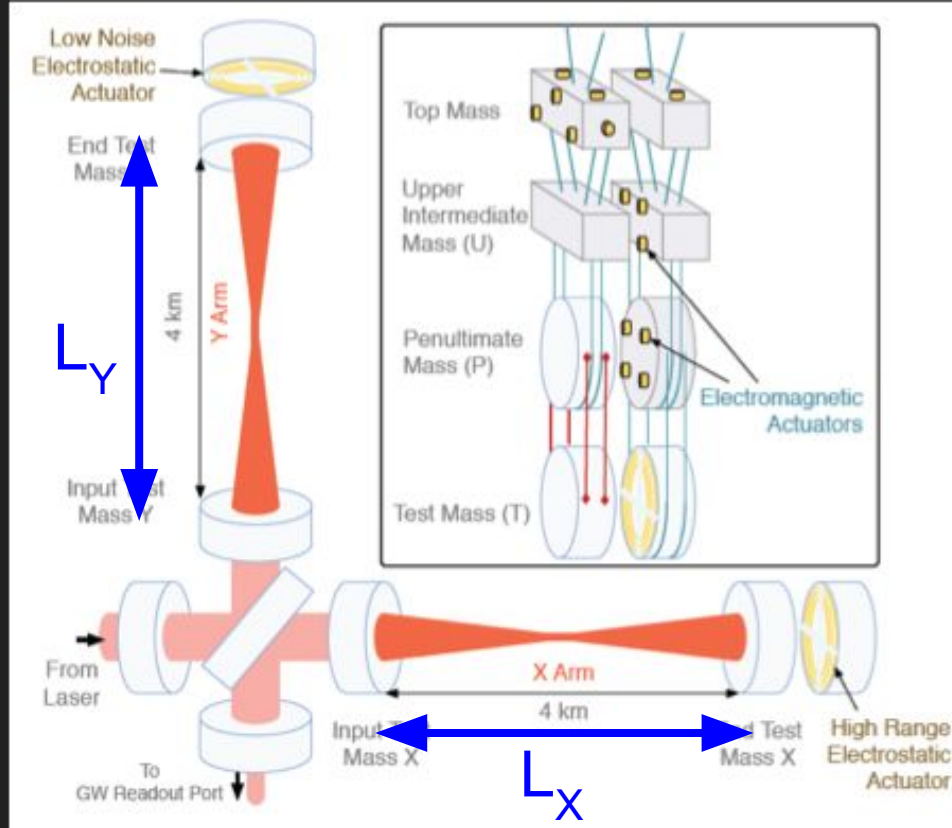
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Mirror displacements in LIGO's quad-suspension pendulum are subdued by actuators



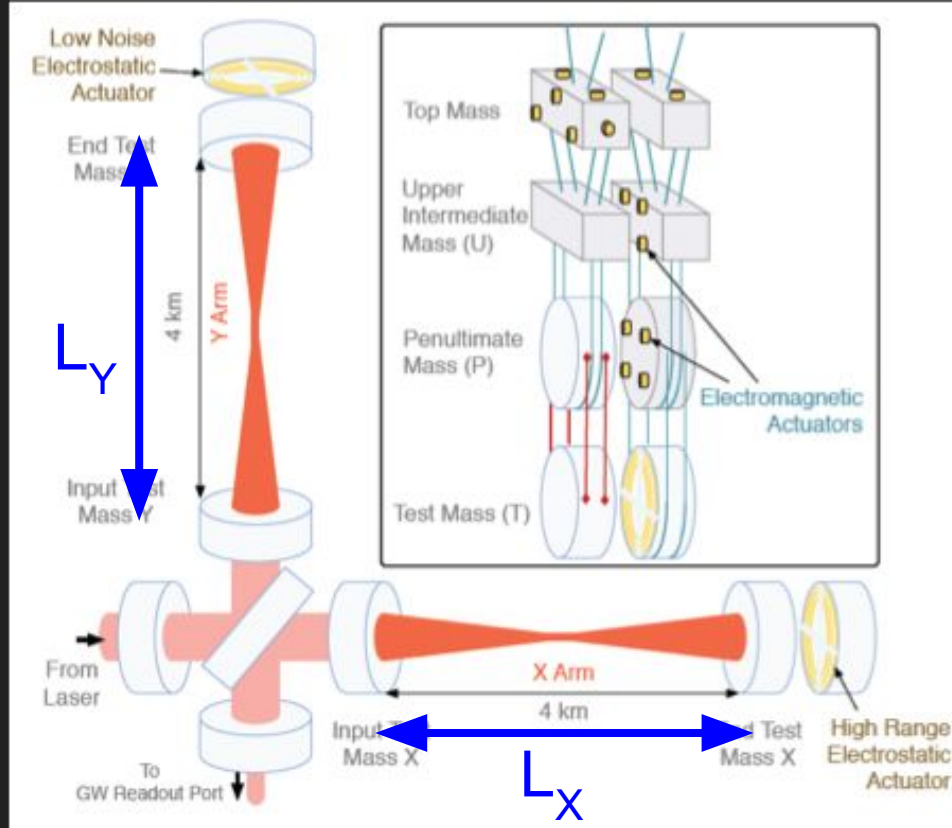
Mirror displacements in LIGO's quad-suspension pendulum are suppressed by actuators



$$\Delta L_{\text{ext}} = L_X - L_Y$$

for free test mass

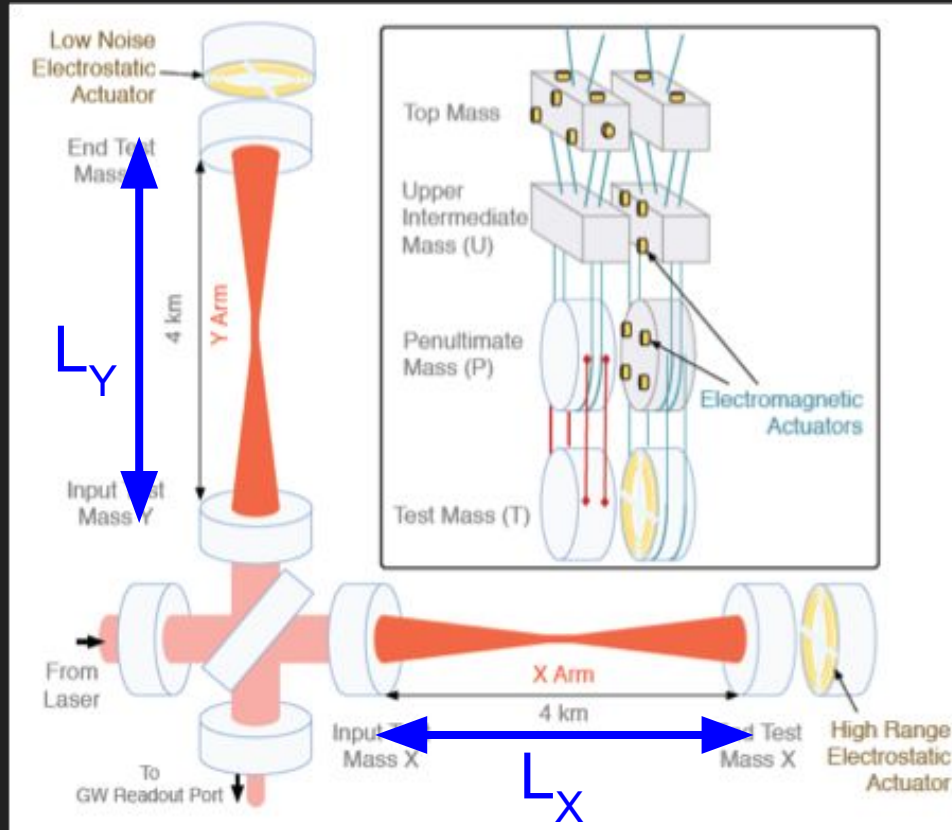
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$\Delta L_{\text{ext}} = L_X - L_Y$
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ΔL_{ctrl} = displacement
from actuators
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motion

Mirror displacements in LIGO's quad-suspension pendulum are suppressed by actuators



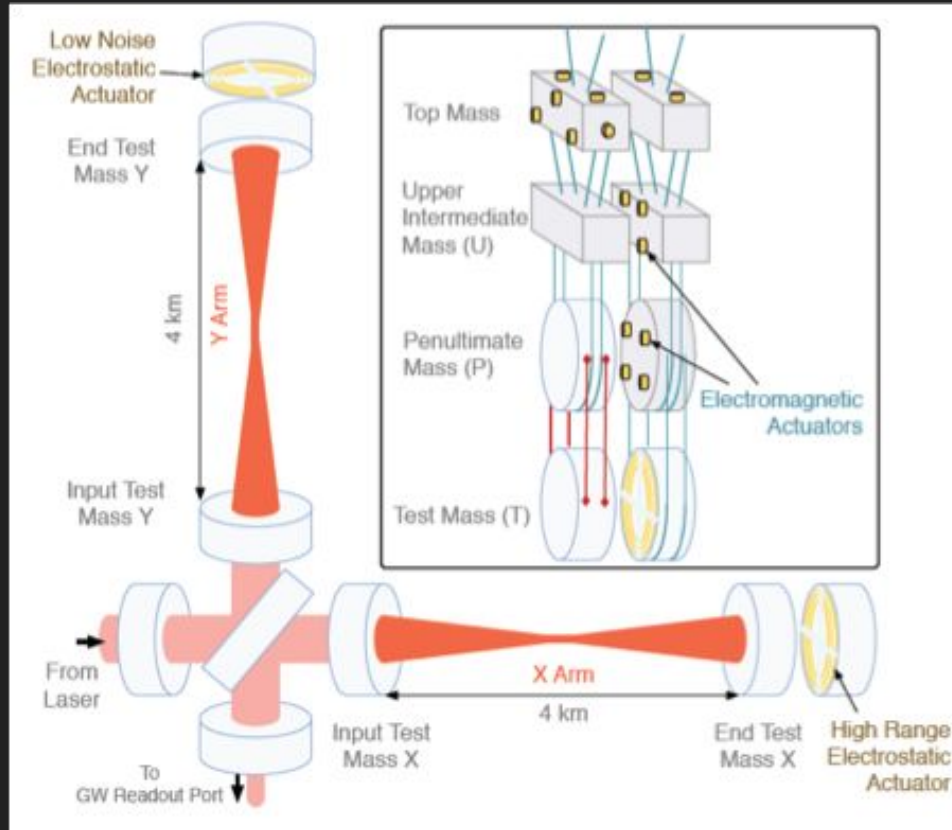
$$\Delta L_{\text{ext}} = L_X - L_Y$$

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ΔL_{ctrl} = displacement
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$$\Delta L_{\text{res}} = \Delta L_{\text{ext}} - \Delta L_{\text{ctrl}}$$

Mirror displacements in LIGO's quad-suspension pendulum are suppressed by actuators

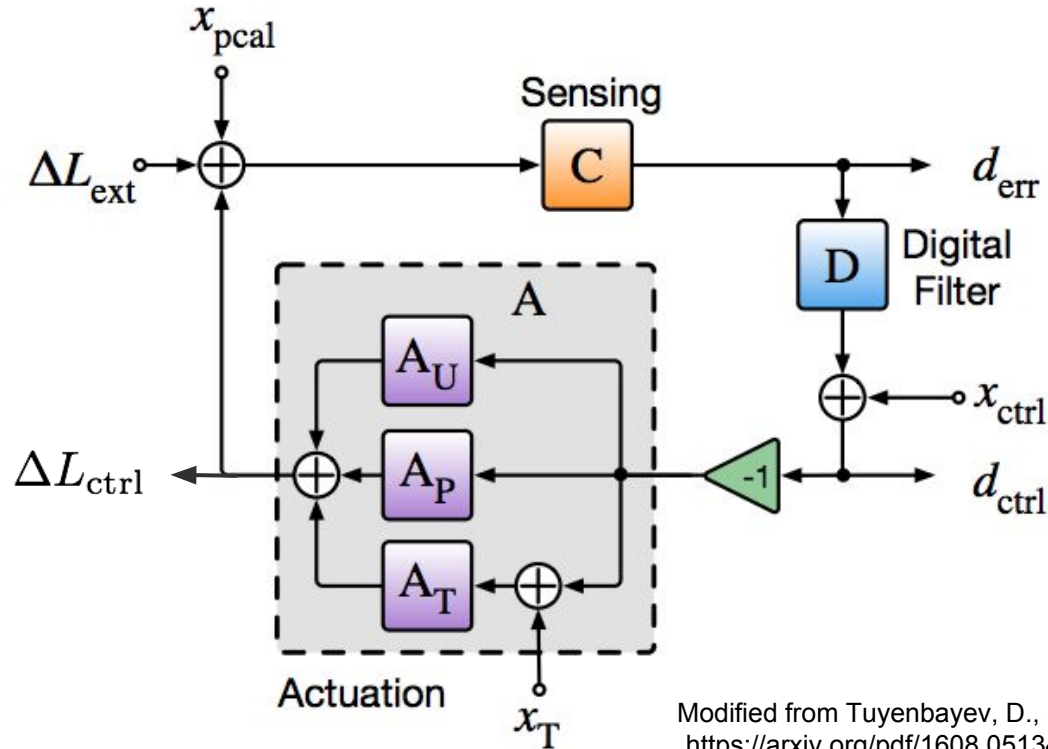


- Note the quad-suspension pendulum with stages:
- Top mass
 - Upper Intermediate Mass (U)
 - Penultimate Mass (P)
 - Test Mass (T)

Outline (3/5)

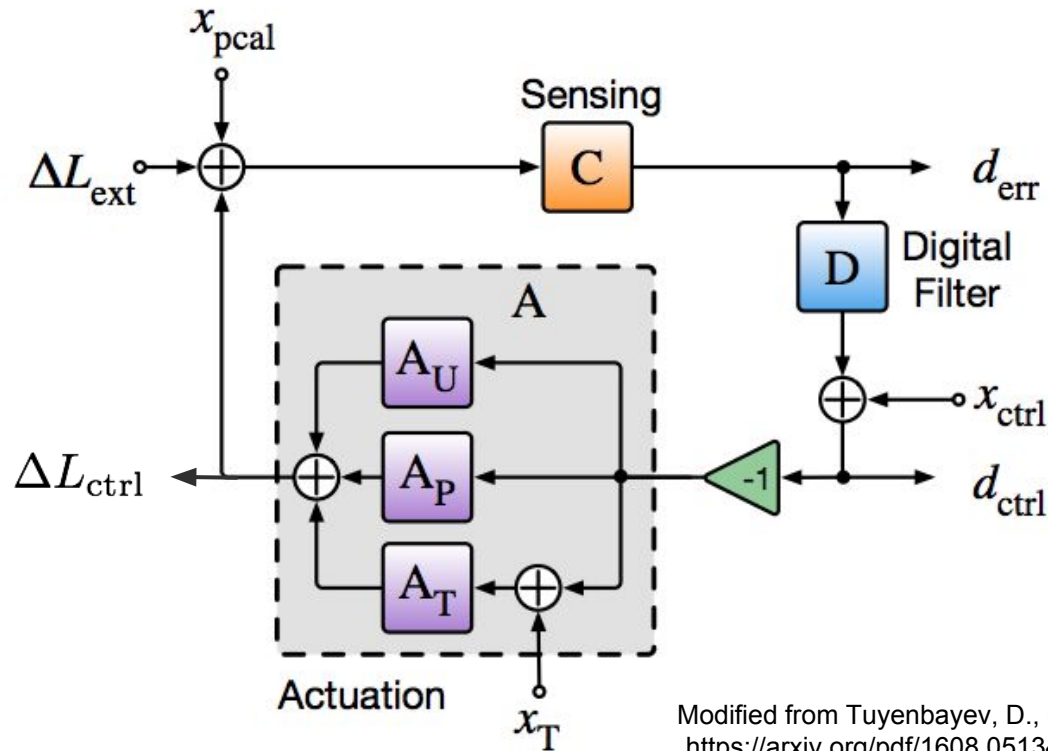
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Schematic of differential arm length control loop



Modified from Tuyenbayev, D., et al.
<https://arxiv.org/pdf/1608.05134.pdf>

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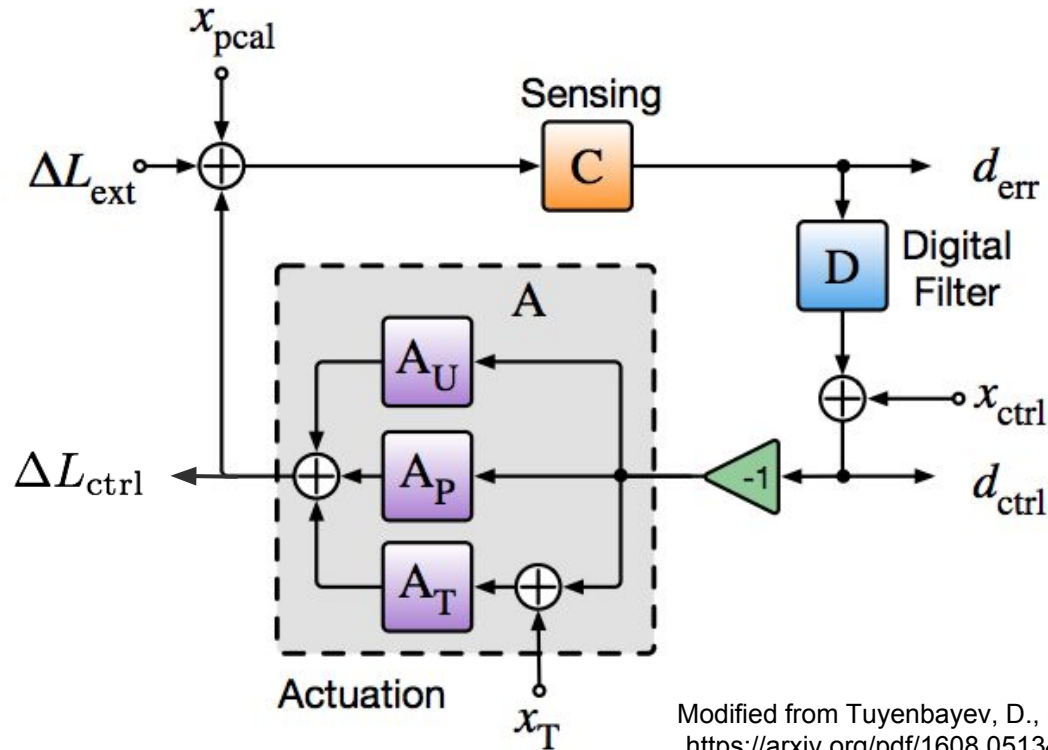


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$\Delta L_{\text{ext}} \rightarrow$ unsuppressed
differential arm length

$\Delta L_{\text{ctrl}} \rightarrow$ control-signal
produced diff. arm length

Schematic of differential arm length control loop



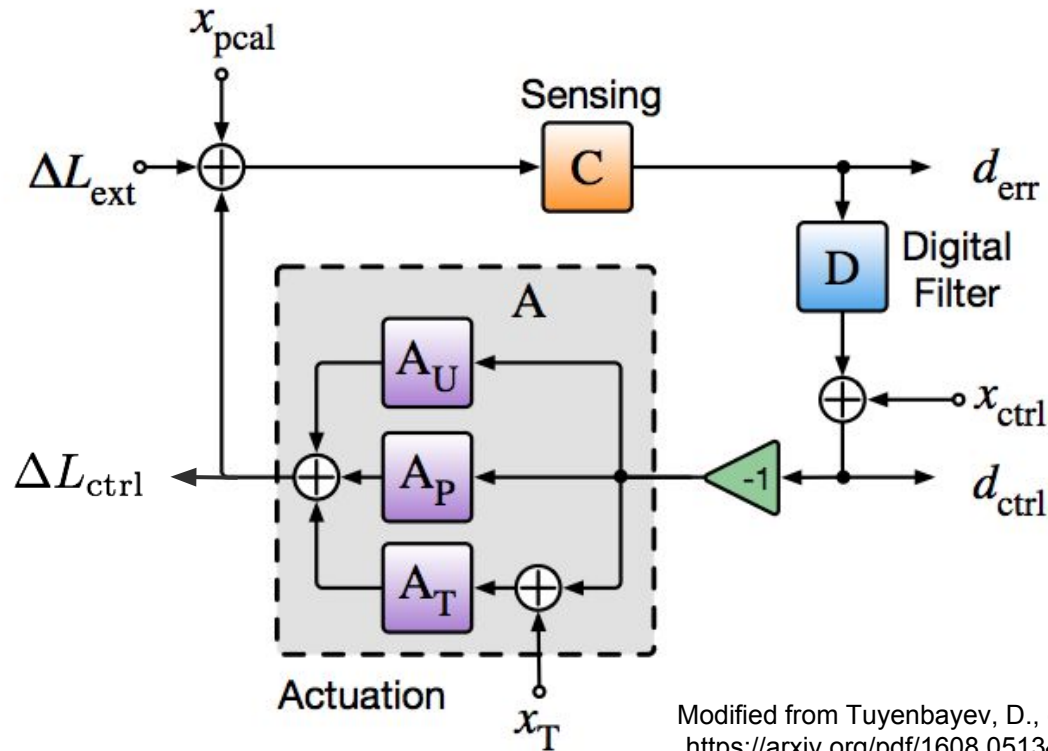
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Schematic of differential arm length control loop



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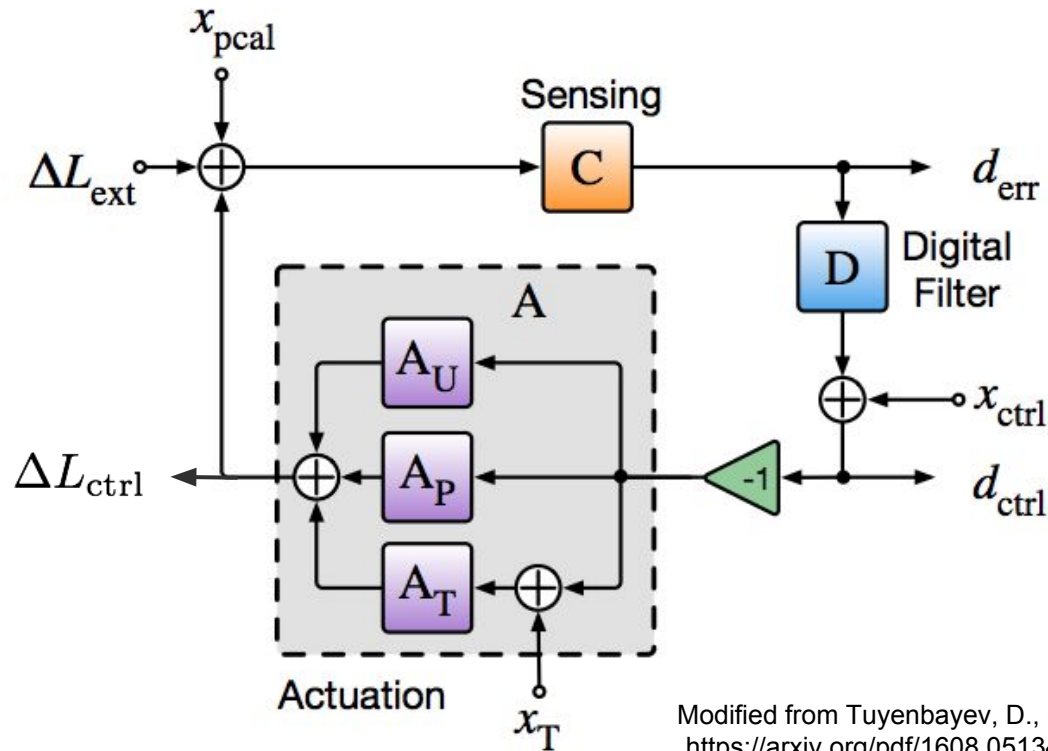
$\Delta L_{\text{ctrl}} \rightarrow$ control-signal produced diff. arm length

$$\Delta L_{\text{res}} = \Delta L_{\text{ext}} - \Delta L_{\text{ctrl}}$$

$d_{\text{err}} \rightarrow$ digital error signal

$d_{\text{ctrl}} \rightarrow$ digital control signal

Schematic of differential arm length control loop



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$d_{\text{err}} \rightarrow$ digital error signal

$d_{\text{ctrl}} \rightarrow$ digital control signal

$$\Delta L_{\text{ext}} = C^{-1} * d_{\text{err}}(t) + A * d_{\text{ctrl}}(t)$$

Sensing and actuation function models

The sensing function $C(f, t)$ is modeled as a single-pole low-pass filter due to the optical response of the signal recycled Fabry-Pérot cavities.

$$C(f, t) = \frac{\kappa_C(t)}{1 + i f / f_C} C_R(f) \exp(-2\pi i f \tau_C)$$

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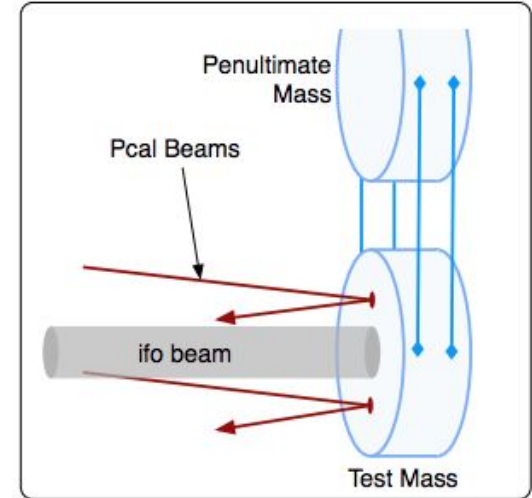
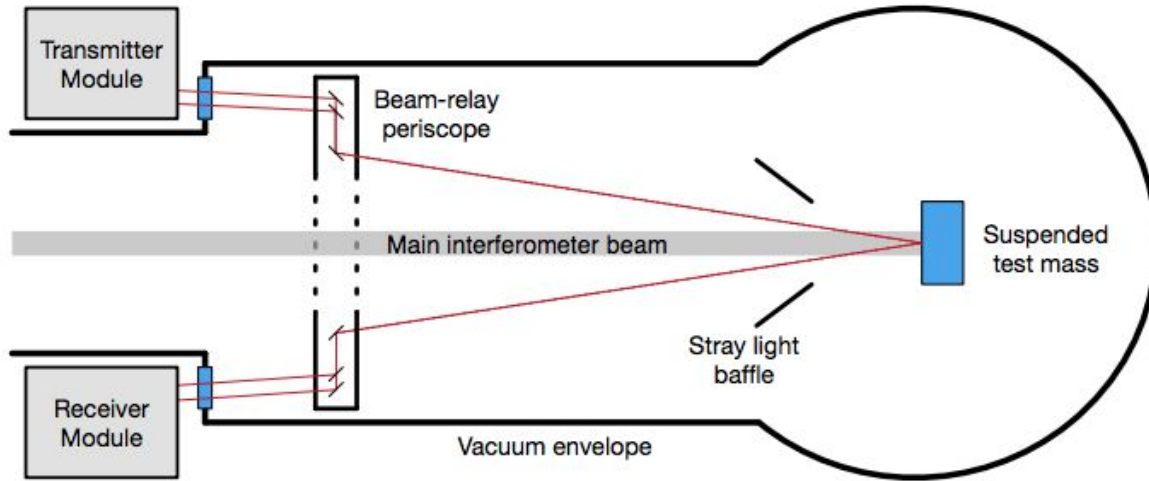
The actuation function $A(f,t)$ is a function of the gain and normalized frequency dependence of the upper intermediate test mass (U), the penultimate mass (P), and the test mass (T)

$$A(f, t) = \kappa_{PU}(A_{P,0}(f) + A_{U,0}(f)) + \kappa_T A_{T,0}(f)$$

Outline (4/5)

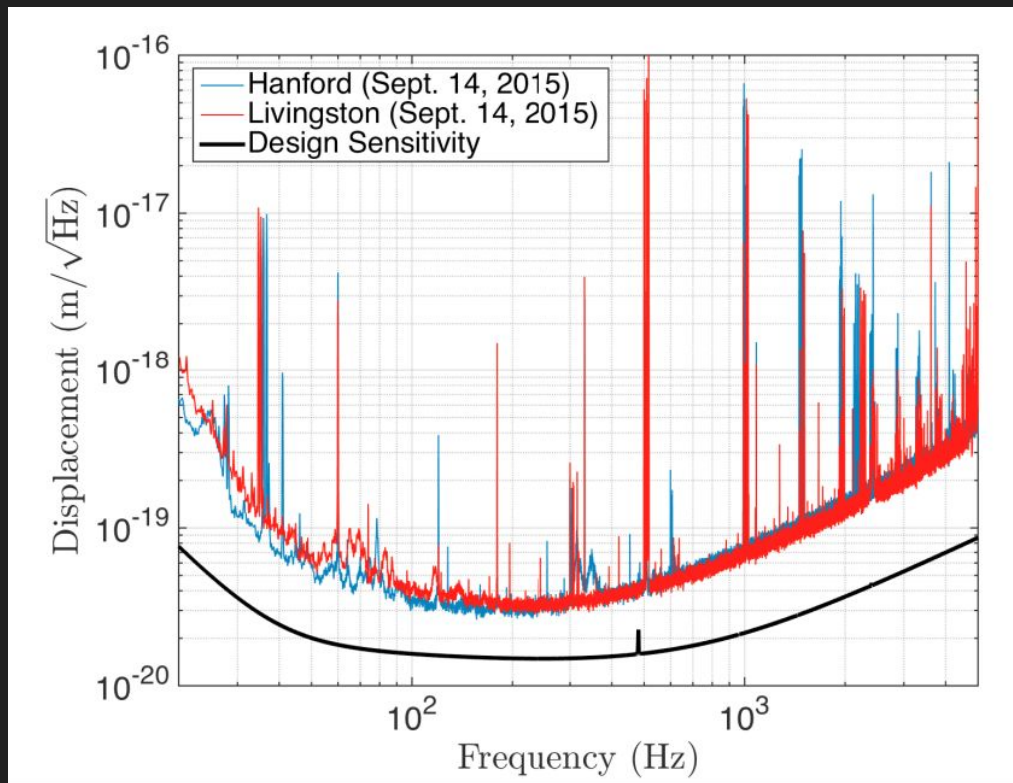
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The photon calibrator uses the response of the test mass to an input laser of known power and frequency to calibrate the interferometer

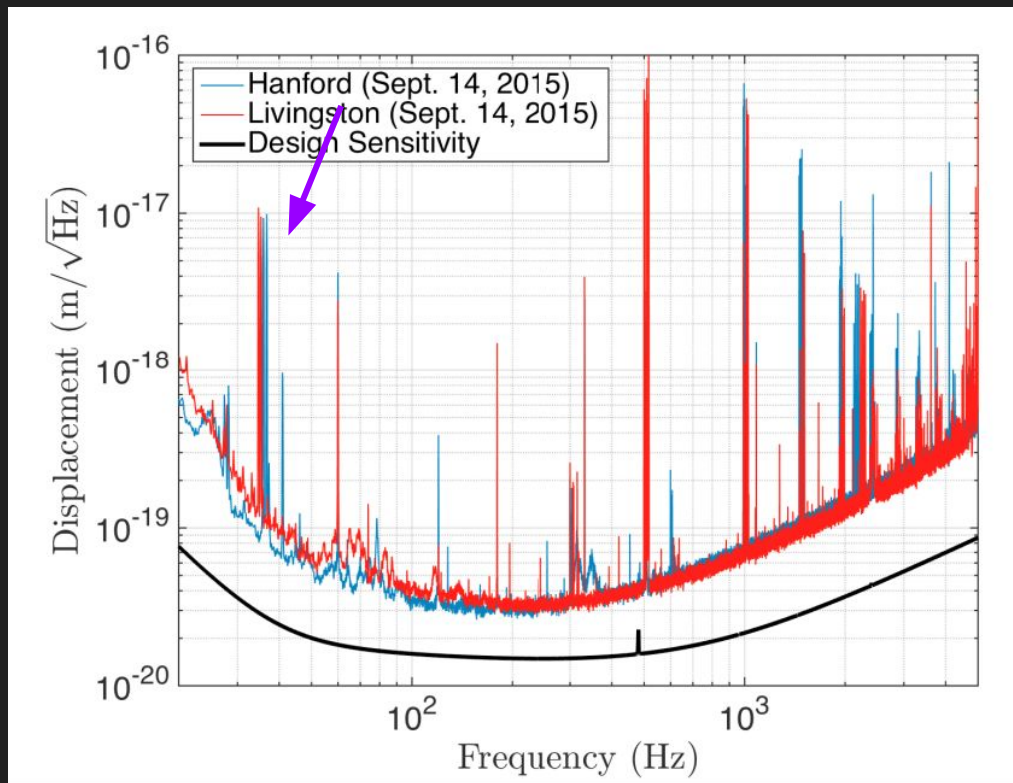


Karki, S., et. al. <https://arxiv.org/pdf/1608.05055.pdf>

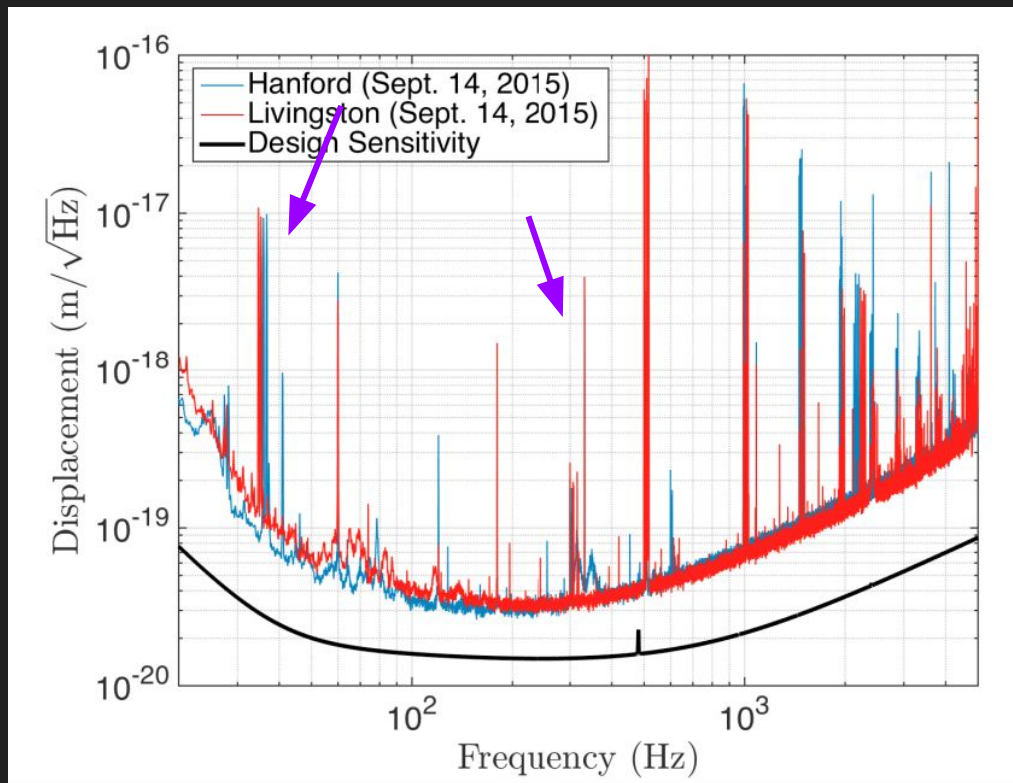
The photon calibrator injects calibration lines at ~ 36 Hz, 331 Hz, 1083 Hz, and 3001 Hz



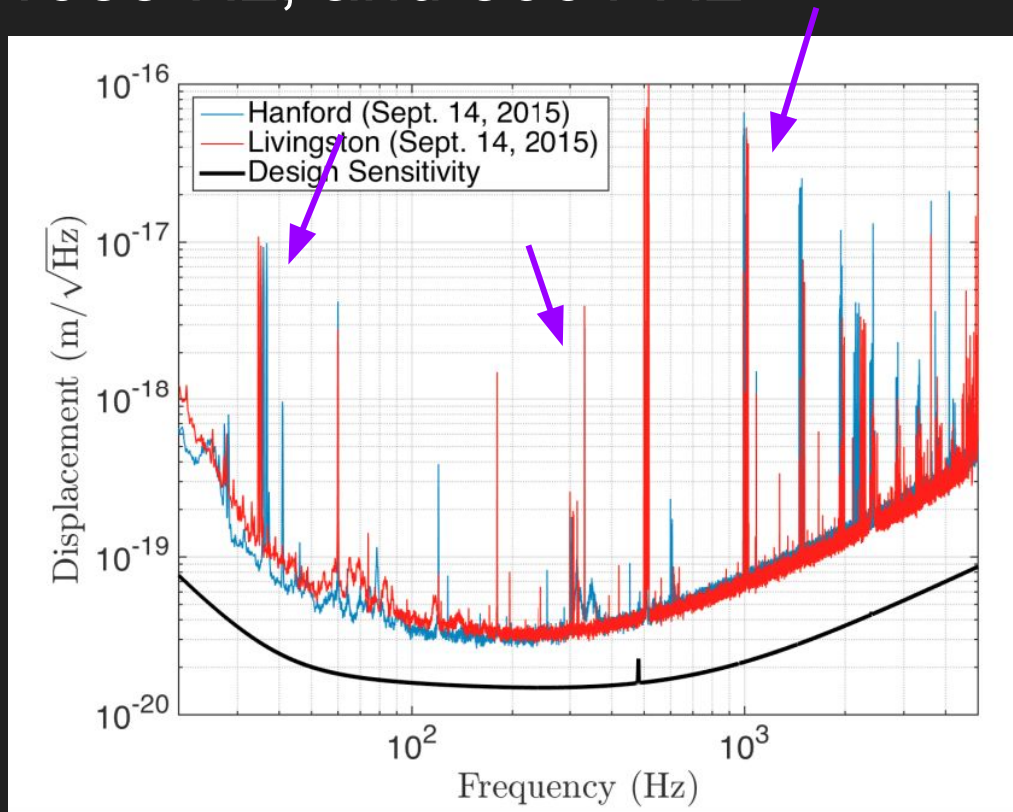
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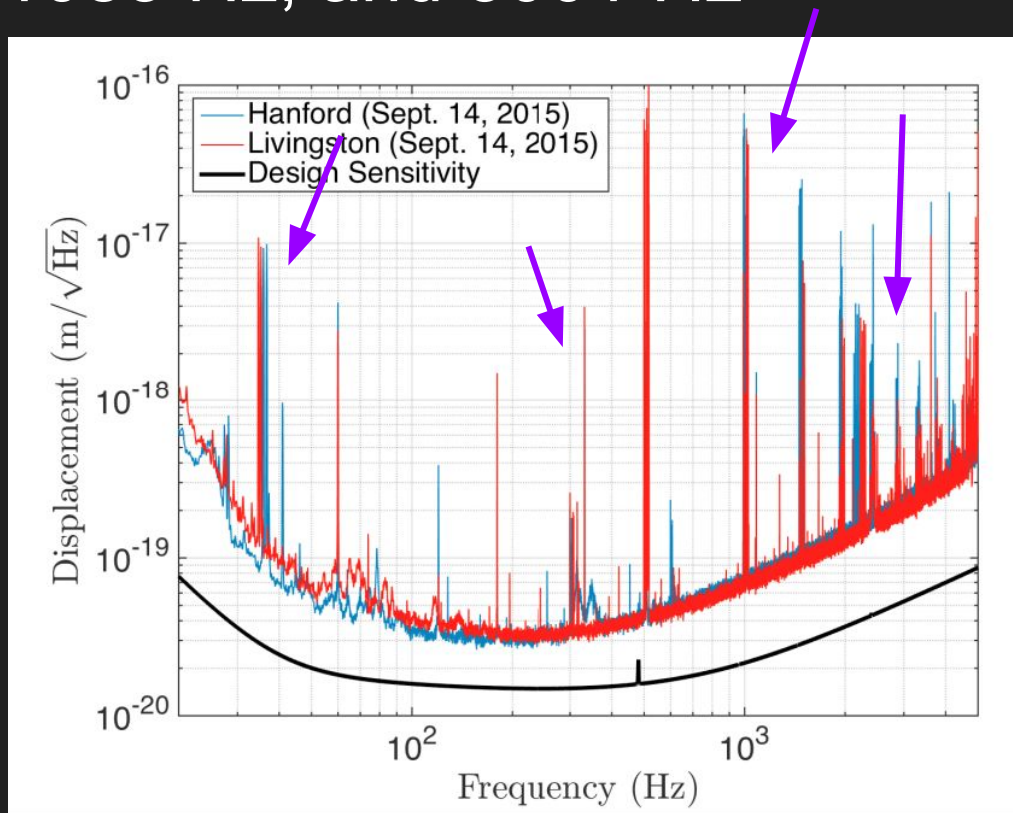
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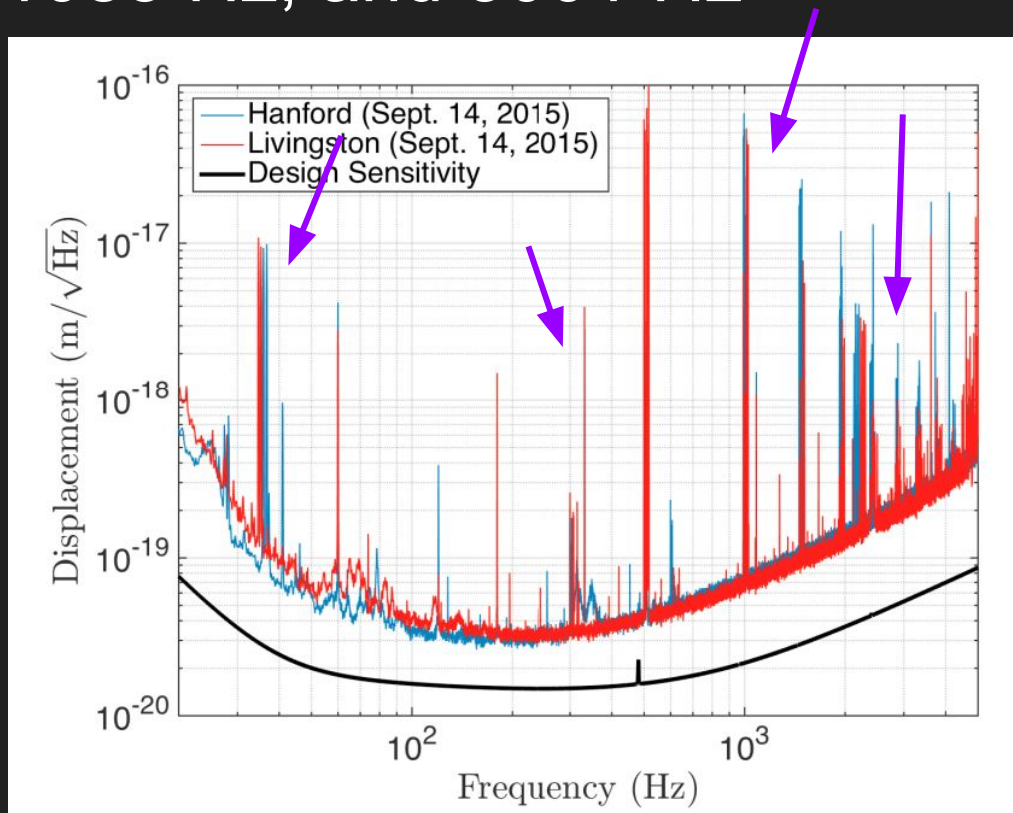


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The photon calibrator injects calibration lines at ~ 36 Hz, 331 Hz, 1083 Hz, and 3001 Hz

Calibration lines are also injected by the actuators (i.e., not Pcal) at ~ 35 Hz (x_{ctrl}) and ~ 37 Hz (x_{tst})



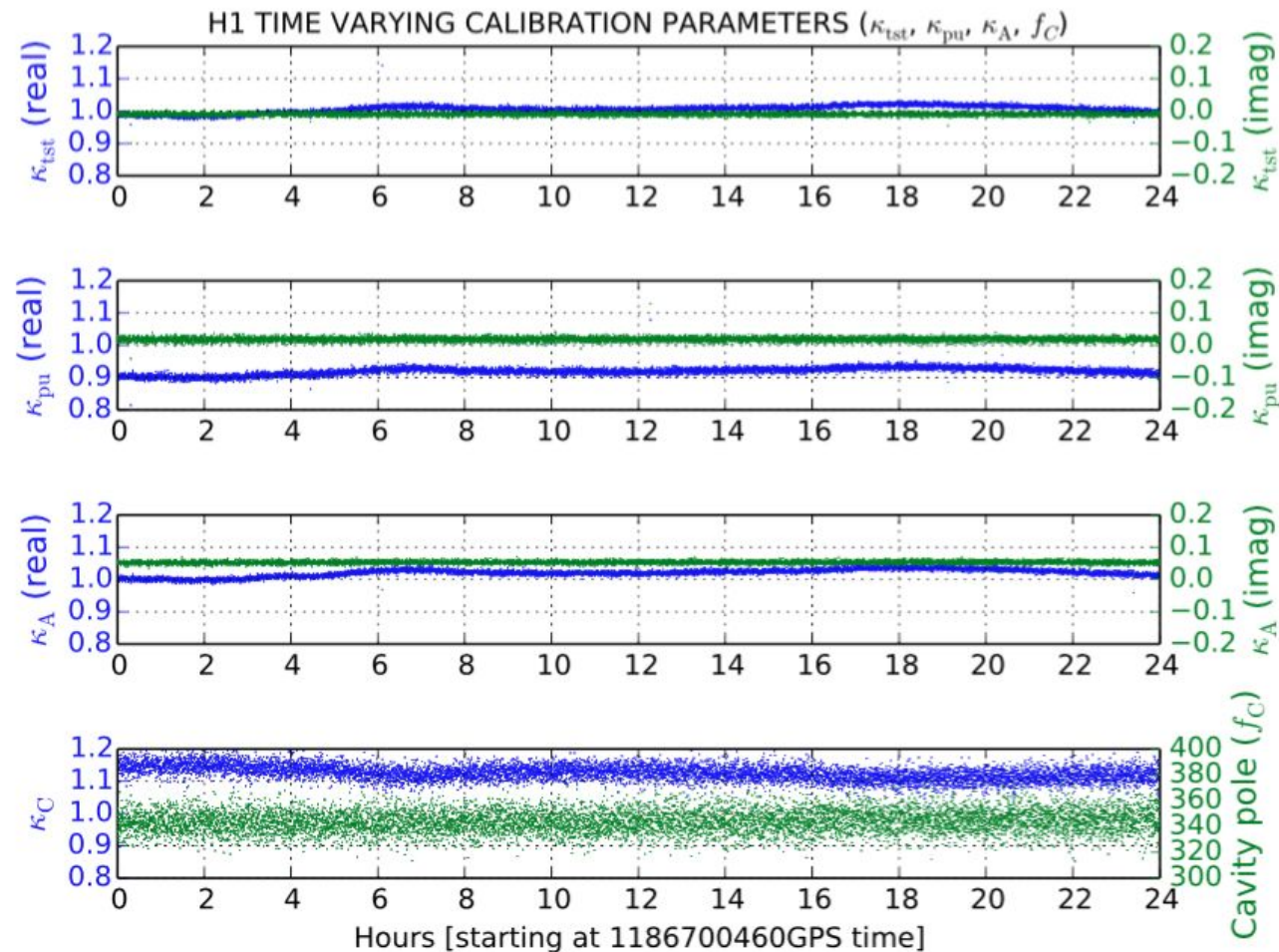
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The Spectral Line Monitoring (SLM) tool functionality

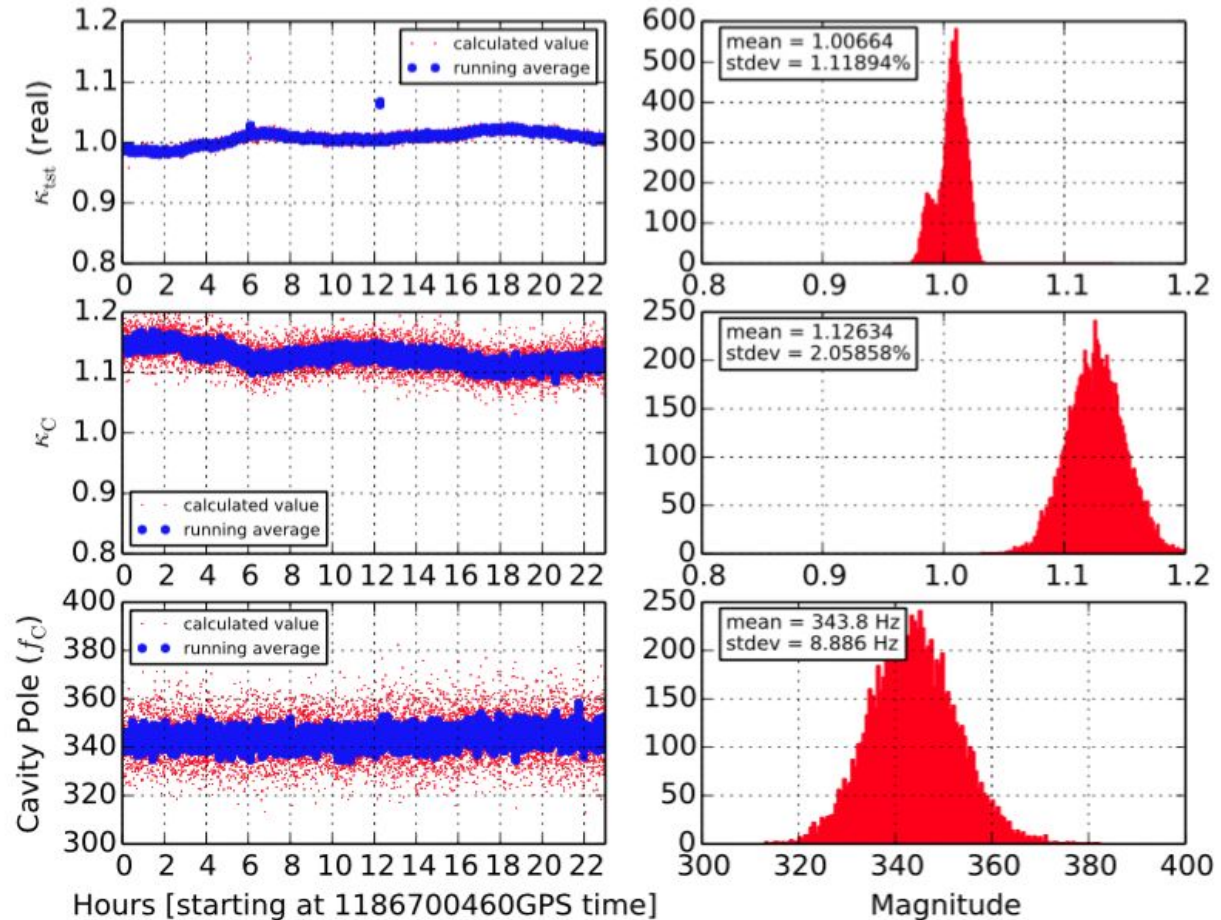
- Tracks the amplitude, phase, and power spectral density of specified frequencies in the LIGO data channels
 - Designed to be a once-per-day diagnostic, not real time
- Creates independent plots of the time varying kappa factors from the sensing and actuation functions, as well as the cavity pole frequency as a function of time
- Calculates and plots ratios of GDS to Pcal and GDS to Front End (DARM_ERR, DARM_CTRL) calibration line amplitudes to discern potential discrepancies
- Plots ratios of transmitted and received Pcal light to discern potential clipping
- Plots other parameters and ratios relevant to Pcal

Example Kappa Plot 1



Example Kappa Plot 2

H1: CALIBRATION PARAMETERS (ESD Actuation (κ_{tst}), Optical Gain (κ_{C}), & Cavity Pole (f_{C}))

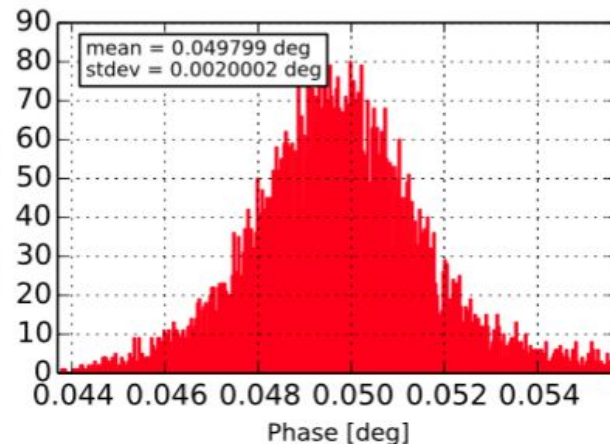
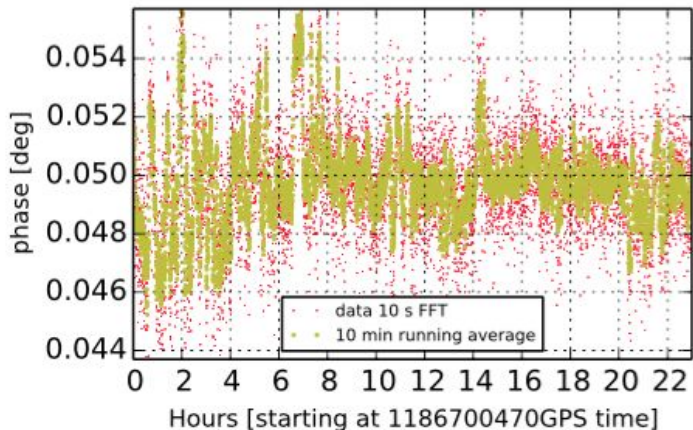
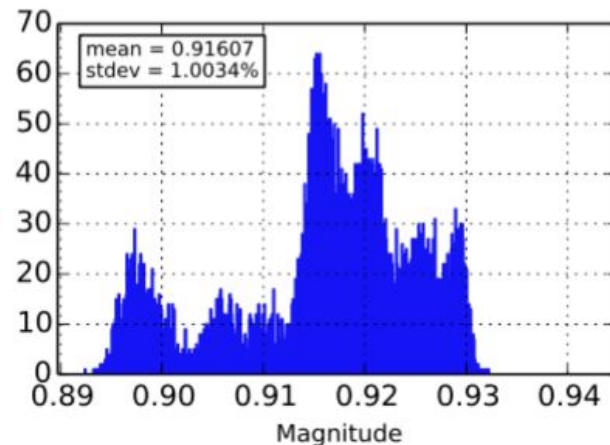
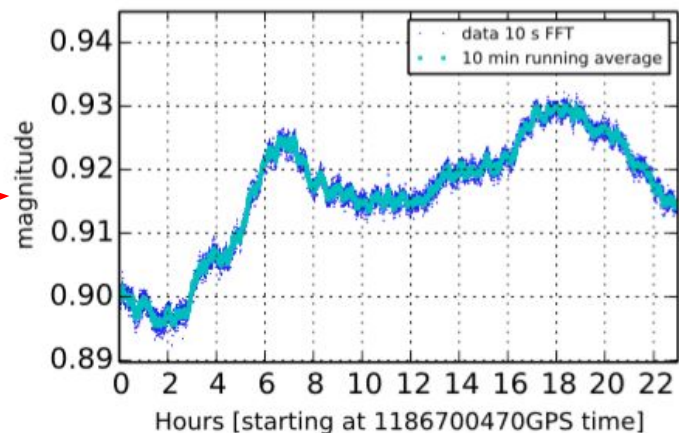


Among other uses, SLM can be used to
see light clipping with Pcal

This ratio
should
always be 1



H1: 331.9 Hz RxPD[m]/TxPD[m]



Conclusion: Not
all of the light
transmitted by
Pcal was
received. Some
of the light must
be clipping
somewhere.

Comparison of current vs. updated SLM Functionality

Current Functionality

- SLM data only output to ascii text file
- EPICS channels needed to be manually updated
- Plotting tools all in MATLAB
 - Needs to recompile every time it is run
 - Proprietary...licence issues

New Functionality

- SLM data output to both ascii text files *and* gwf frame file (e.g., for discovery by NDS2)
 - Allows for easier integration with tools used by control room for plotting
- EPICS channels are updated automatically once per day
- Plotting tools now in Python
 - Does *not* need to recompile every time
 - Free, easier to maintain and integrate with other calibration code

Areas for improvement in SLM

- Hardcoded to do six specific frequencies. If you wanted to add more, then the SLM code would need to be changed.
- Automatically produce plots that compare the kappa values calculated by SLM to the kappa values recorded in online calibration pipeline



Thank you!



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References

E. Anders *et al.* LIGO SURF Final Report: Spectral Line Monitoring Tool. (2013) [[LIGO-P11300120-v2](#)].

S. Karki *et al.* Rev. Sci. Instrum. **87**. no.11, 114503 (2016) doi:10.1063/1.4967303 [[arXiv:1608.05055](#) [astro-ph.IM]].

D. Tuyenbayev *et al.*, Class. Quant. Grav. **34**, no. 1, 015002 (2017) doi:10.1088/02649381/34/1/15002 [[arXiv:1608.05134](#) [astro-ph.IM]].